Rank-based multiple change-points detection in multiple time series

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E LA RECHERCHE À L'INDUSTRI





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- 2 The Bernoulli detector model
 - Change-point model
 - The Wilcoxon rank-sum test
 - Prior on indicators
 - Posterior distribution and implementation

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Context

- Objectives: >
 - infer the functional links
 - detect events

capteurs



signaux

Graph building

Mutual information, correlations, indicators on temporal windows... [XKH11], [CAMGP11], [ASW+06] \rightarrow functional links extracted \rightarrow no temporal information

Multivariate analysis

PCA. ICA. dictionnaries. statistical tests... [LYFLLC11] → excellent temporal resolution

- \rightarrow poor spatial information



segmentation of genetic data [BV11]



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segmentation of genetic data [BV11]

- > Our approach :
 - detection of events (change-points), using structural priors
 - functional relationships inference from a temporal analysis



Goal: off-line multiple segmentation of multivariate time series



> observations \boldsymbol{X} ($K \times N$)

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Approach: statistical test, Bayesian framework, signals dependencies

Bayes' theorem:

```
f(\boldsymbol{R}|\boldsymbol{X}) \propto L(\boldsymbol{X}|\boldsymbol{R})f(\boldsymbol{R})
```

- > posterior $f(\mathbf{R}|\mathbf{X})$: estimation of \mathbf{R}
- > likelihood L(X|R): based on a robust statistical test
- > prior $f(\mathbf{R})$: introduction of the possible links between signals

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Goal: off-line multiple segmentation of multivariate time series



- > observations \boldsymbol{X} ($K \times N$)
- > indicators \mathbf{R} ($K \times N$)

Approach: statistical test, Bayesian framework, signals dependencies

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$f(\boldsymbol{R}|\boldsymbol{X}) \propto L(\boldsymbol{X}|\boldsymbol{R})f(\boldsymbol{R})$

observations X ($K \times N$) $x_{j,i}$ mutually independent

indicators $\boldsymbol{R} (K \times N)$

 $r_{j,i} = \begin{cases} 1 & \text{if } x_{j,i} \text{ is a change-point } (H_1), \\ 0 & \text{otherwise } (H_0), \end{cases}$

for all $1 \le j \le K$, $1 \le i \le N$ by convention $r_1 = r_N = 1$.





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Change-point model for $L_*(\boldsymbol{X}|\boldsymbol{R})$

- > R defines segments for each signal
- > for each $x_{i,i} \in S \rightarrow$ compute p-value $p_{i,i}$, by a statistical test on S
- > p-values:
 - under H_0 : $x_{j,i}$ not a change-point, $r_{j,i} = 0$, $p_{j,i} \sim \mathcal{U}_{[0,1]}$ [SSC99, SBB01]
 - under H_1 : $x_{i,i}$ change-point, $r_{i,i} = 1$, $p_{i,i}$, unknown distribution under H_1 : choice of $\mathcal{B}e(\gamma, 1)$ [SBB01] parameter $\gamma \in (0, 1)$:
 - function of an acceptance level α .
 - $\begin{aligned} &f(\alpha|r=1)=f(\alpha|r=0)\\ \bullet \ \gamma \text{ is therefore the unique solution in }(0,1) \text{ of } \end{aligned}$ $\gamma \alpha^{\gamma - 1} = 1, \forall \alpha \in (0, e^{-1})$



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> marginal densities of the p-values, taken as random variables:

 $f(p_{j,i}|\mathbf{R}) = \begin{cases} & \mathbb{1}_{[0,1]}(p_{j,i}) & \text{if } r_{j,i} = 0 \ (H_0, x_{j,i} \text{ is not a change-point}), \\ & \gamma p_{j,i}^{\gamma - 1} \mathbb{1}_{[0,1]}(p_{j,i}) & \text{if } r_{j,i} = 1 \ (H_1, x_{j,i} \text{ is a change-point}) \end{cases}$

> composite marginal likelihood:

$$L_{*}(\boldsymbol{X}|\boldsymbol{R}) = \prod_{j=1}^{K} \prod_{i=2}^{N-1} \left(\gamma p_{j,i}^{\gamma-1}\right)^{r_{j,i}}$$



- The Wilcoxon / Mann-Whitney rank-sum test is chosen to compute the p-values [Wil45].
- > For two segments Y and Z :
 - compute the statistic $U = \min(U_Y, U_Z)$:



tabulated p-values or normal approximation for large samples

$$z = \frac{U - m_U}{\sigma_U}$$
, with $m_U = \frac{MN}{2}$, $\sigma_U = \sqrt{\frac{MN(M + N + 1)}{12}}$

> High *p*-values when the differences between the pairs of observations from *Y* and *Z* are distributed around 0 (*H*₀) → the data are not assumed to be normally distributed. > Indicators matrix:

$$\boldsymbol{R} = \begin{pmatrix} \dots & 0 \dots 1 \dots 0 \dots 1 \dots 0 \dots \\ \dots & 0 \dots 0 \dots 0 \dots 1 \dots 0 \dots \\ \dots & 1 \dots 0 \dots 0 \dots 0 \dots 0 \dots 0 \dots 0 \dots \\ \dots & 0 \dots 1 \dots 0 \dots 0 \dots 0 \dots 0 \dots 0 \dots 0 \end{pmatrix} \qquad \qquad \boldsymbol{R}_i = \boldsymbol{\epsilon} = (1, 1, 0, 0)^T$$

> Dependency: if the signal k depends on the signal l, then $R_{k,i} = R_{l,i}$ with a high probability

 P_{ϵ} is the probability to observe the configuration ϵ in $R \to P = (P_{\epsilon})_{\epsilon \in \mathcal{E}}$

- > $(R_i)_{2 \le i \le N-1}$ are assumed to be *a priori* independent: $f(\mathbf{R}) = \prod_{i=2}^{N-1} f(R_i)$
- > prior on indicators: $f(\mathbf{R}, \mathbf{P}) \propto f(\mathbf{R}|\mathbf{P})f(\mathbf{P})$, with:
 - $f(\mathbf{R}|\mathbf{P}) = \prod_{\epsilon \in \mathcal{E}} P_{\epsilon}^{S_{\epsilon}(\mathbf{R})}$, $S_{\epsilon}(\mathbf{R})$ is the number of times that the configuration ϵ appears in the columns of \mathbf{R}
 - vague prior for $P: \mathcal{D}_L(d)$ [DTD07]

> finally:

$$f(\boldsymbol{R}, \boldsymbol{P}) \propto \prod_{\epsilon \in \mathcal{E}} P_{\epsilon}^{S_{\epsilon}(\boldsymbol{R}) + d_{\epsilon} - 1}$$



Posterior distribution

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> From the pseudo likelihood and the prior, the posterior expressed as:

$$\begin{split} \boldsymbol{R}, \boldsymbol{P}|\boldsymbol{X}) \propto L_*(\boldsymbol{X}|\boldsymbol{R}) f(\boldsymbol{R}|\boldsymbol{P}) f(\boldsymbol{P}), \\ \propto \left(\prod_{j=1}^K \prod_{i=2}^{N-1} \left(\gamma p_{j,i}^{\gamma-1}\right)^{r_{j,i}}\right) \left(\prod_{\epsilon \in \mathcal{E}} P_{\epsilon}^{S_{\epsilon}(\boldsymbol{R}) + d_{\epsilon} - 1}\right) \end{split}$$

> The vector of hyperparameters P_{ϵ} can be integrated out:

$$f(\boldsymbol{R}|\boldsymbol{X}) \propto \left(\prod_{j=1}^{K} \prod_{i=2}^{N-1} (\gamma p_{j,i}^{\gamma-1})^{r_{j,i}} \right) \times \frac{\prod_{\epsilon \in \mathcal{E}} \Gamma(S_{\epsilon}(\boldsymbol{R}) + d_{\epsilon})}{\Gamma(N+L)}$$

Algorithm

- > Estimation of the maximum a posteriori of R
- > Monte Carlo by Markov Chain method
- > Gibbs sampling to draw the indicators matrix R, column by column



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Choice of the Gibbs sampler

- > Single change-point in univariate signal
- > Several noise levels:

$$SNR = 10\log\frac{(\mu_k - \mu_l)^2}{\sigma^2}.$$

> Detection performances:

$$recall = \frac{TP}{TP + FN}$$
 $precision = \frac{TP}{TP + FP}$

- > Gibbs sampler: 2 strategies
 - blocked Gibbs sampling
 - conditional probabilities does not form a compatible joint model → pseudo Gibbs sampling

$$R = (..., 0, 1, 0, ..., 0, [r_{i-1}, r_i, r_{i+1}], 0, ..., 0, 1, 0, ...)$$

$$P_{val} = (..., \cdot, [p_{i-1}], \cdot, ..., \cdot, [p_{i-1}, p_i, p_{i+1}], ..., \cdot, [p_{i+1}], \cdot, ...)$$



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$$R = (..., 0, 1, 0, ..., 0, \boxed{r_i}, 0, ..., 0, 1, 0, ...)$$
$$P_{val} = (..., \cdot, p_{i^-}, \cdot, ..., \cdot, \boxed{p_i}, \cdot, ..., \cdot, p_{i^+}, \cdot, ...)$$



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Impact of data distribution

Comparison with the fused lasso [Tib11] ($\lambda=22.3)$ and the Bernoulli Gaussian model

Observations on segment k:







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Control of the false discovery rate (FDR)

Definition:

- > multiple hypothesis testing
- > maximizing the probability of detecting the true positive by controlling the false positives

 $FDR = E\left[\frac{V}{R \lor 1}\right], V =$ number of false positives, R = number of positives

Control of the FDR:

> m tests independent \rightarrow Benjamini-Hochberg procedure [BH95]

> our model:

- p-values computed by the statistical test highly dependent
- control by acceptance level α



$$L_{*}(X|R) = \prod_{2=1}^{N-1} \left(\gamma p_{i}^{\gamma-1}\right)^{r_{i}}$$

Figure: $FDR = f(\alpha)$, 320 points, 15 change-points, SNR = 5 dB



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Household electrical power consumption

- > 4 time series
- > Dependencies known ightarrow noninformative or informative prior on P



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Household electrical power consumption

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Array Comparative Genomic Hybridization

- > Tumorous cells: deregulations in DNA copy number
- > Samples: transcription of the chromosomes of patients, labelled with red fluorescent molecules
- > Hybridization with reference gene copies, labelled with green fluorescent molecules
- > Measure of the log_2 -ratio
- > Objective: to localize the DNA portions over or under-expressed [AGH⁺02, BV11]



Bernoulli detector model, all patients jointly





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Group fused lasso [BV11], all patients jointly



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Fused lasso [Tib11], $\lambda = 3.0$, each patient 53 individually





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Conclusion

Advantages

- > non parametric, robust statistical test, high power for the change-point model we choose
- > weak assumptions on the data distribution
- > flexible dependency structure learning, or used to improve the segmentation
- > FDR controlled by α (empirically)

Drawbacks, limitations

- > high complexity (linear with the number of configurations €), MCMC method → slow, can't handle large number of time series
- composite marginal likelihood, dependency between the p-values
- > approximation by the pseudo Gibbs sampler
- > control of the FDR not formalized

Future work

- > higher dimensions
- > likelihood:
 - other statistical tests (Student's t-test, Welch's t-test...)
 - semi-parametric approach with the empirical likelihood [Owe10]
- > dependency structure:
 - estimation of the causality from \widehat{P}
 - graphical representation

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Thank you for your attention !



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